

# YAJING SHEN

**Professor**

**Associate Director** | Cheng Kar-Shun Robotics Institute

**Director** | Center for Smart Manufacturing

Department of Electronic & Computer Engineering

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Google Scholar: <https://scholar.google.com/citations?user=-Q68e0AAAAJ&hl>

## BIOGRAPHY

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Prof. **Yajing Shen** received his B.S. (2005) and M.S. (2008) degrees in Mechanical and Automation Engineering from Xi'an Jiaotong University, and his PhD (2012) in Micro/Nano System Engineering at Nagoya University, Japan. He is currently a Professor in the Department of Electronic and Computer Engineering and has served as the Director of the Center for Smart Manufacturing at The Hong Kong University of Science and Technology (HKUST), Hong Kong, China. Prior to joining HKUST, he was as Assistant Professor and later an Associate Professor in the Department of Mechanical and Biomedical Engineering at The City University of Hong Kong (CityUHK).

Prof. **Shen's** research interests mainly focus on intelligent robotic systems, particularly in bioinspired miniature robotics and human-robot interaction. He has published over 200 peer-reviewed papers, including in top multidisciplinary journals such as *Science Robotics* (2), *Science Advances* (2), *Nature Communications* (6), *PNAS* (1), as well as leading specialized robotic journals like *IEEE Trans on Robotics*. His work has garnered widespread attention from international media, including Associated Press, Thomson Reuters, AAAS, CCTV, TVB, etc.

Prof. **Shen** is a Senior Member of IEEE, and serves as Vice-Chair of the IEEE Hong Kong Magnetism Chapter and Co-Chair of IEEE Nano Technology Council Nano-Biomedicine Technical Committee. He is also an Executive Member of several organizations in China, including the China Automation Society Robotic Technical Committee, China Micro-nano Robot Society, China Coexisting-Cooperative-Cognitive Robot Society, and China Instrument Sensory Society. He was an Associate Editor for the flagship robotic journal *IEEE Trans on Robotics* (2019-2022) and currently serves on the editorial boards of *Engineering* (IF>10) and *Cyborg and Bionic Systems* (IF>10).

As an educator at the university, Prof. **Shen** strives not only to teach UG / PG courses, but also to ignite student interest, foster critical thinking, and cultivate their ability to self-learning and innovation. He has supervised 15 PhD students, 13 of whom are continuously pursuing academic careers at TOP universities, 6 receiving the "NSFC Excellent Young Scientists Overseas" award (formerly Young Thousand Talents Program) shortly after graduation.

Prof. **Shen** has received several prestigious awards, including the Best Manipulation Paper Award at the IEEE International Conference on Robotics and Automation (*ICRA*), the IEEE Robotics and Automation Society Japan Chapter Young Award, the Hong Kong UGC Early Career Award, the Big-on-Small Award at MARSS, and the 2018 China Top 10 scientific and technological progress in robotics, the 2025 Hong Kong Top 10 Scientific and technological progress and so on. He was also honored as Outstanding Supervisor, IEEE Distinguished Lecturer, and the National Excellent Young Scientist.

Prof. **Shen** has been elected a Member of the Hong Kong Young Academy of Sciences, and a Fellow of the International Academy of Artificial Intelligence Science in recognition of his academic contributions. He was also selected as a Fellow of the HKUST Founders' Club and named a Hong Kong Young Scientist of Entrepreneur in recognition of his efforts and contributions to technology transfer.

## EMPLOYMENT & EDUCATION

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**Hong Kong University of Science and Technology**

*Sept 2022 - Present*

Professor (2025-) / Associate Professor (2022), Department of Electronic and Computer Engineering

**City University of Hong Kong**

*Jun 2013 - Aug 2022*

Associate Professor (2019) / Assistant Professor (2013), Department of Biomedical Engineering

Nagoya University

Oct 2008 - Mar 2013

Postdoc (2012-13), Micro/Nano System Engineering

PhD (2008-12), Micro/Nano System Engineering (Supervisor: [Toshio FUKUDA](#))

Xi'an Jiaotong University

Sept 2001 - Apr 2008

Master (2005-08), Mechanical and Automation Engineering (Supervisor: [Shengdun ZHAO](#))

Bachelor (2001-05), Mechanical and Automation Engineering

## TEN REPRESENTATIVE WORKS

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1. H. Ren, L. Yang, H. Chang, T. Zhang, G. Li, X. Yang, Y. Tang, W. Shang, **Y. Shen\***, "A Robust and Omnidirectional-sensitive Electronic Antenna for Tactile-induced Perception," *Nature Communications*, 16, 3135, 2025.
2. Y. Tang, G. Li, T. Zhang, H. Ren, X. Yang, L. Yang, D. Guo, **Y. Shen\***, "Digital Channel-Enabled Distributed Force Decoding via Small Datasets for Hand-Centric Interactions," *Science Advances*, 11, eadt2641, 2025.
3. T. Zhang, G. Li, H. Ren, L. Yang, X. Yang, R. Tan, Y. Tang, D. Guo, H. Zhao, W. Shang, **Y. Shen\***, "Sub-Millimeter Fiberscopic Robot with Integrated Maneuvering, Imaging, and Biomedical Operation Abilities," *Nature Communications*, 15, 10874, 2024. (Editors' Highlights: one of the 50 best papers recently published in the area of "Devices")
4. R. Tan, X. Yang, H. Lu, **Y. Shen\***, "One-step formation of polymorphous sperm-like microswimmers by vortex turbulence-assisted microfluidics", *Nature Communications*, 15, 4761, 2024. (Editors' highlights: one of the 50 best papers recently published in the area of "Applied physics and mathematics")
5. Y. Yang, **Y. Shen\***, "A liquid metal-based module emulating the intelligent preying logic of flytrap", *Nature Communications*, 15, 3398, 2024.
6. X. Yang, R. Tan, H. Lu, T. Fukuda, **Y. Shen\***, "Milli-scale cellular robots that can reconfigure morphologies and behaviors simultaneously", *Nature Communications*, 13 (1), 1-11, 2022.
7. P. Wang, M. A. R. Azad, X. Yang, P. Martelli, K.Y. Cheung, J. Shi\*, **Y. Shen\***, "Self-adaptive and efficient propulsion of Ray sperms at different viscosities enabled by heterogeneous dual helixes", *PNAS*, 118(23), 2021.
8. Y. Yan, Z. Hu, Z. Yang, W. Yuan, C. Song, J. Pan\*, **Y. Shen\***, "Bio-inspired soft tactile sensor with self-decoupling and super-resolutive ability", *Science Robotics*, 6(51), 2021. (highlighted by *Science through video*)
9. X. Yang, W. Shang, H. Lu, Y. Liu, L. Yang, R. Tan, X. Wu\*, **Y. Shen\***, "An agglutinate magnetic spray transforms inanimate objects into millirobots for biomedical applications", *Science Robotics*, 5(48), 2020. (featured by *CCTV*)
10. H. Lu, M. Zhang, Y. Yang, Q. Huang, T. Fukuda, Z. Wang\*, **Y. Shen\***, "A bioinspired multilegged millirobot that functions in both dry and wet conditions", *Nature Communications*, 9(3944), 2018. (top 5 most read *Nature Communications* articles in physics in 2018; top 10 progress in Robotics in China in 2018)

## PUBLICATIONS (SELECTED)

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### Journal

1. H. Ren, L. Yang, H. Chang, T. Zhang, G. Li, X. Yang, Y. Tang, W. Shang, **Y. Shen\***, "A Robust and Omnidirectional-sensitive Electronic Antenna for Tactile-induced Perception," *Nature Communications*, 16, 3135, 2025.
2. X. Yang, H. Ren, D. Guo, Z. Ling, T. Zhang, G. Li, Y. Tang, H. Zhao, J. Wang, H. Chang, G. Ki, J. Dong, N. Wu, **Y. Shen\***, "A Soft Tactile Unit with 3D Force and Temperature Mathematical Decoupling Ability for Robots," *Engineering* (2025).

3. Y. Tang, G. Li, T. Zhang, H. Ren, X. Yang, L. Yang, D. Guo, **Y. Shen\***, “Digital Channel-Enabled Distributed Force Decoding via Small Datasets for Hand-Centric Interactions,” *Science Advances*, 11, eadt2641, 2025.
4. T. Zhang, G. Li, H. Ren, L. Yang, X. Yang, R. Tan, Y. Tang, D. Guo, H. Zhao, W. Shang, **Y. Shen\***, “Sub-Millimeter Fiberscopic Robot with Integrated Maneuvering, Imaging, and Biomedical Operation Abilities,” *Nature Communications*, 15, 10874, 2024.
5. R. Tan, X. Yang, H. Lu, **Y. Shen\***, “One-step formation of polymorphous sperm-like microswimmers by vortex turbulence-assisted microfluidics”, *Nature Communications*, 15, 4761, 2024.
6. Y. Yang, **Y. Shen\***, “A liquid metal-based module emulating the intelligent preying logic of flytrap”, *Nature Communications*, 15, 3398, 2024.
7. T. Zhang, H. Ren, G. Li, P. Wang, W. Shang, **Y. Shen\***, “High-Precise Metallic Helical Microstructure Fabrication by Rotational Nanorobotic Manipulation System With Tilted Mandrel Compensation”, *IEEE/ASME Transactions on Mechatronics*, 29 (1): 214-223, 2024.
8. L. Yang, T. Zhang, H. Huang, H. Ren, W. Shang\*, **Y. Shen\***, “An on-wall-rotating strategy for effective upstream motion of untethered millirobot: principle, design and demonstration”, *IEEE Transactions on Robotics*, 39 (3): 2419-2428, 2023.
9. J. Miao, T. Zhang, G. Li, D. Guo, S. Sun, R. Tan, J. Shi, **Y. Shen\***, “Flagellar/Ciliary Intrinsic Driven Mechanism Inspired All-in-One Tubular Robotic Actuator”, *Engineering*, 23, 170-180, 23, 170-180, 2023.
10. S. Sun, J. Miao, R. Tan, T. Zhang, G. Li, **Y. Shen\***, “Asymmetric Soft-Structure Functional Surface for Intelligent Liquids’ Distinction, Transportation, and Reaction Mixer”, *Advanced Functional Materials*, 33(1), 2209769, 2023.
11. T. Zhang, G. Li, X. Yang, H. Ren, D. Guo, H. Wang, K. Chan, Z. Ye, T. Zhao, C. Zhang, W. Shang\*, **Y. Shen\***, “A Fast Soft Continuum Catheter Robot Manufacturing Strategy Based on Heterogeneous Modular Magnetic Units”, *Micromachines*, 14(5), 911, 2023.
12. J. Miao, S. Sun, T. Zhang, G. Li, H. Ren, **Y. Shen\***, “Natural Cilia and Pine Needles Combinedly Inspired Asymmetric Pillar Actuators for All-Space Liquid Transport and Self-Regulated Robotic Locomotion”, *ACS Applied Materials & Interfaces*, 14 (44), 50296-50307, 2022.
13. H. Huang, Y. Feng, X. Yang, **Y. Shen\***, “Natural gum-based electronic ink with water-proofing self-healing and easy-cleaning properties for directly on-skin electronics”, *Biosensors and Bioelectronics*, 214, 114547, 2022.
14. Y. Tang, T. Zhang, H. Ren, W. Zhang, G. Li, D. Guo, L. Yang, R. Tan, **Y. Shen\***, “Highly sensitive spherical cap structure-based iontronic pressure sensors by a mold-free fabrication approach”, *Smart Materials and Structures*, 31 (9), 095030, 2022.
15. X. Yang, R. Tan, H. Lu, T. Fukuda, **Y. Shen\***, “Milli-scale cellular robots that can reconfigure morphologies and behaviors simultaneously”, *Nature Communications*, 13 (1), 1-11, 2022.
16. L. Yang, J. Miao, G. Li, H. Ren, T. Zhang, D. Guo, Y. Tang, W. Shang\*, **Y. Shen\***, “Soft Tunable Gelatin Robot with Insect-like Claw for Grasping, Transportation, and Delivery”, *ACS Applied Polymer Materials*, 4(8), 5431, 2022.
17. J. Miao, T. Zhang, G. Li, W. Shang, **Y. Shen\***, “Magnetic artificial cilia carpets for transport, mixing, and directional diffusion”, *Advanced Engineering Materials*, 24 (7), 2101399, 2022.
18. Y. Yang, X. Li, **Y. Shen\***, “Electrode Array-Free Tactile Sensor for Addressable Force Sensing Assisted by a Neural Network”, *ACS Applied Polymer Materials*, 4(6), 4551–4557, 2022.
19. W. Shang, H. Lu, Y. Yang, **Y. Shen\***, “7-DoFs Rotation-Thrust Microrobotic Control for Low-Invasive Cell Pierce via Impedance Compensation”, *IEEE/ASME Transactions on Mechatronics*, 2022.

20. R. Tan, X. Yang, H. Lu, L. Yang, T. Zhang, J. Miao, Y. Feng, **Y. Shen\***, “Nanofiber-based biodegradable millirobot with controllable anchoring and adaptive stepwise release functions”, *Matter*, 5(4), 1277-1295, 2022.
21. L. Yang, T. Zhang, R. Tan, X. Yang, D. Guo, Y. Feng, H. Ren, Y. Tang, W. Shang, **Y. Shen\***, “Functionalized Spiral-Rolling Millirobot for Upstream Swimming in Blood Vessel”, *Advanced Science*, 2200342, 2022.
22. X. Yang, R. Tan, H. Lu, **Y. Shen\***, “Magnetic-Directed Manipulation and Assembly of Fragile Bioartificial Architectures in the Liquid-Liquid Interface”, *IEEE/ASME Transactions on Mechatronics*, 2022.
23. Y. Yan, Z. Hu, **Y. Shen\***, J. Pan\*, “Surface Texture Recognition by Deep Learning-Enhanced Tactile Sensing”, *Advanced Intelligent Systems*, 4(1), 2100076, 2022.
24. D. Guo, G. Li, J. Miao, **Y. Shen\***, “A smartphone-based calibration-free portable urinalysis device”, *Journal of Central South University*, 28(12), 3829-3837, 2021.
25. J. Miao, T. Zhang, G. Li, W. Shang, **Y. Shen\***, “Magnetic artificial cilia carpets for transport, mixing, and directional diffusion”, *Advanced Engineering Materials*, 2101399, 2021.
26. G. Li, T. Zhang, **Y. Shen\***, “Transparent Magnetic Soft Millirobot Actuated by Micro-Node Array”, *Advanced Materials Technologies*, 6(8), 2100131, 2021.
27. P. Wang, M. A. R. Azad, X. Yang, P. Martelli, K.Y. Cheung, J. Shi\*, **Y. Shen\***, “Self-adaptive and efficient propulsion of Ray sperms at different viscosities enabled by heterogeneous dual helixes”, *PNAS*, 118(23), 2021.
28. Y. Yan, Z. Hu, Z. Yang, W. Yuan, C. Song, J. Pan\*, **Y. Shen\***, “Bio-inspired soft tactile sensor with self-decoupling and super-resolutive ability”, *Science Robotics*, 6(51), 2021.
29. Y. Yang, **Y. Shen\***, “Light-driven carbon-based materials: principle, robotization, and applications” *Advanced Optical Materials*, 2100035, 2021.
30. X. Yang, R. Tan, H. Lu, **Y. Shen\***, “Starfish inspired milli soft robot with omnidirectional adaptive locomotion ability”, *IEEE Robotics and Automation Letters*, 6(2), 3325-3332, 2021.
31. T. Zhang , L. Yang , X. Yang , R. Tan , H. Lu\* and **Y. Shen\***, “Millimeter-Scale Soft Continuum Robots for Large-Angle and High-Precision Manipulation by Hybrid Actuation”. *Advanced Intelligent Systems*, 3(2), 2000189, 2021.
32. S. Wang, X. Wei\*, H. Lu, Z Ren, Z. Jiang, J. Ren, Z. Yang, L. Sun, W. Shang, X. Wu and **Y. Shen\***, “Robot-aided fN-m torque sensing within an ultrawide dynamic range”, *Microsystems & Nanoengineering*, 7(1), 1-11, 2021.
33. Y. Yang, Y. Liu, and **Y. Shen\***, “Plasmonic-Enhanced Graphene Oxide-Based Aquatic Robot for Target Cargo Delivery”, *ACS Applied Materials & Interfaces*, 13(1), 2020.
34. X. Yang, W. Shang, H. Lu, Y. Liu, L. Yang, R. Tan, X. Wu\*, **Y. Shen\***, “An agglutinate magnetic spray transforms inanimate objects into millirobots for biomedical applications”, *Science Robotics*, 5(48), 2020.
35. H. Lu, Y. Hong, Y. Yang, Z. Yang\*, and **Y. Shen\***, “Battery-less soft millirobot that can move, sense, and communicate remotely by coupling magnetic and piezoelectric effects”, *Advanced Science*, 7(13), 2000069, 2020.
36. D. Li, C. Liu, Y. Yang, L. Wang\* and **Y. Shen\***, “Micro-rocket robot with all-optic actuating and tracking in the blood”, *Light: Science & Applications*, 9(84), 2020.
37. Y. Yang, Y. Liu, and **Y. Shen\***, “Plasmonic-Assisted Graphene Oxide Films with Enhanced Photothermal Actuation for Soft Robots”, *Advanced Functional Materials*, p1910172, 2020.

38. P. Wang, H. Lu, **Y. Shen\***, “Flexible 3D Helix Fabrication by In-situ SEM Micro Manipulation System”, *IEEE Transactions on Industrial Electronics*, 67(7), 5565-5574, 2019.
39. Y. Liu, G. Li, H. Lu, Y. Yang, Z. Liu, W. Shang\*, **Y. Shen\***, “Magnetically Actuated Heterogeneous Microcapsule-Robot for the Construction of 3D Bioartificial Architectures”, *ACS applied materials & interfaces*, 11(29), 25664-25673, 2019.
40. Y. Liu, C. Wu, H. Lu, Y. Yang, W. Li, and **Y. Shen\***, “Programmable higher-order biofabrication of self-locking microencapsulation”, *Biofabrication*, 11(3), 035019, 2019.
41. H. Lu, Y. Yang, X. Lin, P. Shi, and **Y. Shen\***, “Low-Invasive Cell Injection based on Rotational Microrobot”, *Advanced Biosystems*, 3(7), 1800274, 2019.
42. W. Ding, Y. Zhang, H. Lu, W. Wan, and **Y. Shen\***, “Automatic 3D Reconstruction of SEM images based on Nano-robotic Manipulation and Epipolar Plane Images”, *Ultramicroscopy*, 200, 149-159, 2019.
43. Y. Wen, H. Lu, **Y. Shen\***, and H. Xie\*, “Nanorobotic Manipulation System for 360° Characterization Atomic Force Microscopy”, *IEEE Transactions on Industrial Electronics*, 67(4), 2916-2924, 2019.
44. P. Wang, D. Li, S. Shen, and **Y. Shen\***, “Automatic Microwaveguide Coupling Based on Hybrid Position and Light Intensity Feedback”, *IEEE/ASME Transactions on Mechatronics*, 24(3), 1166-1175, 2019.
45. Y. Yang, D. Li, and **Y. Shen\***, “Inchworm-Inspired Soft Robot With Light-Actuated Locomotion”, *IEEE Robotics and Automation Letters*, 4(2), 1647-1652, 2019.
46. Y. Yang, M. Zhang, D. Li, and **Y. Shen\***, “Graphene-Based Light-Driven Soft Robot with Snake-Inspired Concertina and Serpentine Locomotion”, *Advanced Materials Technologies*, 4(1), 1800366, 2019. [\[html\]](#)
47. H. Lu, Y. Wen, H. Zhang, H. Xie\*, and **Y. Shen\***, “360° multiparametric imaging atomic force microscopy: A method for three-dimensional nanomechanical mapping”, *Ultramicroscopy*, 196, 83-87, 2019.
48. H. Lu, Y. Liu, Y. Yang, X. Yang, R. Tan, **Y. Shen\***, “Self-assembly magnetic chain unit for bulk biomaterial actuation”, *IEEE Robotics and Automation Letters*, 4(2), 262-268, 2018.
49. Y. Liu, Y. Liu, **Y. Shen\***, “Nano-assembly and welding of gold nanorods based on DNA origami and plasmon-induced laser irradiation”, *International Journal of Intelligent Robotics and Applications*, 2(4), 445-453, 2018.
50. H. Lu, M. Zhang, Y. Yang, Q. Huang, T. Fukuda, Z. Wang\*, **Y. Shen\***, “A bioinspired multilegged millirobot that functions in both dry and wet conditions”, *Nature Communications*, 9(3944), 2018.
51. W. Wan, Y. Liu, H. Lu, and **Y. Shen\***, “Investigation of the Nonaxisymmetric Bending Property of Pollen Tubes via a Rotary Nanorobotic System”, *IEEE Transactions on Nanotechnology*, 18, 139-143, 2018.
52. H. Lu, P. Wang, R. Tan, X. Yang, **Y. Shen\***, “Nanorobotic System for Precise In Situ Three-Dimensional Manufacture of Helical Microstructures”, *IEEE Robotics and Automation Letters*, 3(4), 2846-2853, 2018.
53. P. Wang, S. Shen, H. Lu, **Y. Shen\***, “Precise Watch-Hand Alignment Under Disturbance Condition by Microrobotic System”, *IEEE Transactions on Automation Science and Engineering*, 16(1), 278-285, 2018.
54. H. Lu, Y. Liu, Y. Yang, P. Wang, **Y. Shen\***, “Specimen’s plane misaligned installation solution based on charge fluctuation inside SEM”, *Applied Physics Letters*, 112(14), 2018.

55. H. Lu, W. Shang, H. Xie\*, **Y. Shen\***, “Ultrahigh Precise Rotational Positioning under Microscope: Nanorobotic System, Modeling, Control and Applications”, *IEEE Transactions on Robotics*, 34(2), pp. 497-507, 2018.
56. D. Li, Y. Liu, Y. Yang, **Y. Shen\***, “A fast and powerful swimming microrobot with serrate-tail enhanced propulsion interface”, *Nanoscale*, 10 (42), 19673-19677, 2018.
57. Y. Yang, S. Shen, K. Lui, K. Lee, J. Chen, H. Ding, L. Liu, H. Lu, L. Duan, C. Wang, **Y. Shen\***, “Ultrasonic robotic system for noncontact small object manipulation based on Kinect gesture control”, *International Journal of Advanced Robotic Systems*, 14(6), 1729881417738739, 2017.
58. P. Wang, H. Lu, S. Shen, W. Shang, J. Wang, and **Y. Shen\***, “Micro-robotic Manipulation at Time-varying Air-liquid Interface for High-precise Watch-hand Alignment”, *IEEE/ASME Transactions on Mechatronics*, 22 (6), 2017.
59. **Y. Shen\***, W. Wan, H. Lu, T. Fukuda, and W. Shang, “Automatic Sample Alignment under Microscopy for 360° Imaging Based on the Nanorobotic Manipulation System”, *IEEE Transactions on Robotics*, 33(1), pp. 220-226, 2017.
60. Y. Liu, C. Wu, H. Lai, Y. Liu, W. Li, and **Y. Shen\***, “Three-dimensional calcium alginate hydrogel assembly via tiopc-based light-induced controllable electrodeposition”, *Micromachines*, 8(6), 192, 2017.
61. H. Lu, W. Shang, X. Wei, Z. Yang, T. Fukuda, and **Y. Shen\***, “Nanorobotic System iTRo for Controllable 1D Micro/nano Material Twisting Test”, *Scientific Reports*, 7(1), 2017.
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63. W. Shang, D. Li, H. Lu, T. Fukuda, and **Y. Shen\***, “Less-invasive non-embedded cell cutting by nanomanipulation and vibrating nanoknife”, *Applied Physics Letters*, 110(4), 2017.
64. G. Dai, B. Wang, S. Xu, Y. Lu\*, and **Y. Shen\***, “Side-to-Side Cold Welding for Controllable Nanogap Formation from ‘dumbbell’ Ultrathin Gold Nanorods”, *ACS Applied Materials and Interfaces*, 8(21), 13506-13511, 2016.
65. G. Dai, W. Wan, Y. Zhao, Z. Wang, W. Li, P. Shi, and **Y. Shen\***, “Controllable 3D alginate hydrogel patterning via visible-light induced electrodeposition”, *Biofabrication*, 8(2), 2016.
66. W. Shang, H. Lu, W. Wan, T. Fukuda, and **Y. Shen\***, “Vision-based Nano Robotic System for High-throughput Non-embedded Cell Cutting”, *Scientific Reports*, 6, 2016.
67. W. Wan, G. Dai, L. Zhang, and **Y. Shen\***, “Paper-Based Electrodeposition Chip for 3D Alginate Hydrogel Formation”, *Micromachines*, 6(10), 1546-1559, 2015.
68. **Y. Shen\***, M. Nakajima, Z. Zhang, and T. Fukuda, “Dynamic Force Characterization Microscopy Based on Integrated Nanorobotic AFM and SEM System for Detachment Process Study”, *IEEE/ASME Transactions on Mechatronics*, 20(6), pp. 3009-3017, 2015.
69. **Y. Shen\***, Z. Zhang, and T. Fukuda, “Bending spring rate investigation of nanopipette for cell injection”, *Nanotechnology*, 26 (15), 2015.
70. **Y. Shen\***, T. Fukuda, “State of the art: micro-nanorobotic manipulation in single cell analysis”, *Robotics and Biomimetics*, 1(1), 1-13, 2014.
71. **Y. Shen\***, M. Nakajima, Z. Yang, H. Tajima, Z. Najdovski, M. Homma, and T. Fukuda, “Single cell stiffness measurement at various humidity conditions by nanomanipulation of a nano-needle”, *Nanotechnology*, 24(14), 145703, 2013.

72. **Y. Shen\***, M. Nakajima, Z. Yang, S. Kojima, M. Homma, and T. Fukuda, "Design and characterization of nanoknife with buffering beam for insitu single-cell cutting", *Nanotechnology*, 22(30), 305701, 2011.
73. **Y. Shen\***, M. Nakajima, M. Ridzuan Ahmad, S. Kojima, M. Homma, and T. Fukuda, "Effect of ambient humidity on the strength of the adhesion force of single yeast cell inside environmental-SEM", *Ultramicroscopy*, vol. 111, no. 8, pp. 1176-1183, 2011.
74. **Y. Shen\***, M. Nakajima, S. Kojima, M. Homma, M. Kojima, and T. Fukuda, "Single cell adhesion force measurement for cell viability identification using an AFM cantilever-based micro putter", *Measurement Science and Technology*, 22(11), 2011.
75. **Y. Shen\***, M. Nakajima, S. Kojima, M. Homma, and T. Fukuda, "Study of the time effect on the strength of cell-cell adhesion force by a novel nano-picker", *Biochemical and Biophysical Research Communications*, 409(2), pp. 160-165, 2011.
76. **Y. Shen\***, M. R. Ahmad, M. Nakajima, S. Kojima, M. Homma, and T. Fukuda, "Evaluation of the single yeast cell's adhesion to ITO substrates with various surface energies via ESEM nanorobotic manipulation system", *IEEE Transactions on Nanobioscience*, 10(4), pp. 217-224, 2011.

### Conference

1. H. Lu, W. Wan, **Y. Shen\***, "Nanorobotic manipulation system for in-situ micro/nano torsion test", in *International Conference on Complex Medical Engineering (ICME)*, 2017. (Best Paper Finalist)
2. **Y. Shen\***, M. Nakajima, S. Kojima, M. Homma, Y. Ode, and T. Fukuda, "Characterization of oscillating nano knife for single cell cutting by nanorobotic manipulation system inside ESEM", in *IEEE International Conference on Robotics and Automation (ICRA)*, 2011. (Best Manipulation Paper Award)
3. **Y. Shen\***, M. Nakajima, M. Ahmad, S. Kojima, M. Homma, and T. Fukuda, "In-situ single cell manipulation via nanorobotic manipulation system inside E-SEM", in *IEEE International Conference on Micro-NanoMechatronics and Human Science (MHS)*, 2009. (Best Paper Award)

### Book/Book Chapter

1. R. Tan, X. Yang, **Y. Shen**, "Minimalist milliscale robot construction by M-spray", *Untethered Small-Scale Robots for Biomedical Applications*, 2023.
2. T. Fukuda, M. Nakajima, M. Takeuchi, Y. Hasegawa, T. Yue, C. Hu, M. Ahmad and **Y. Shen**, "Chapter 12: 3D System Cell Engineering Using Micro-Nano Robotics", *The Encyclopedia of Medical Robotics*, 2018.
3. **Y. Shen**, "In Situ Nano Characterization of Yeast Cells using ESEM and FIB", *Advanced Microscopy in Mycology*, 2015.
4. **Y. Shen**, T. Fukuda, "Nanomanipulation of Biocells", *Encyclopedia of Nanotechnology*, 2015.

### Patent

1. **Y. Shen**, X. Yang, Z. Ling, "Object Property Estimation and Manipulation Based on Multi-Finger Tactile Information", US 63/620,146, Filed, Jan 11, 2024.
2. **Y. Shen**, X. Yang, "Bioinspired sensing unit with decoupled force and temperature sensing ability", US 63/589,989, Filed, Oct 12, 2023.
3. **Y. Shen**, "Artificial Skin-based Phygital System for the Cohesion of Human, Robot, and Virtual World", US 63/507,737, Filed, Jun 13, 2023.
4. **Y. Shen**, "Flexible mechanochromic tactile sensor and a method of distributed tactile measurement using the sensor", US 63/478,499, Filed, Jan 4, 2023.

5. **Y. Shen**, “Low-cost tactile sensor based on artificial magnetic pillar for robotic tactile sensing”, US 63/478,501, Filed, Jan 4, 2023.
6. **Y. Shen**, “An entirely biodegradable spiny milli-ball robot (SMB-bot) for oral macromolecule drug delivery”, US 63/478,497, Filed, Jan 4, 2023.
7. **Y. Shen**, X. Yang, “Method for converting inanimate object to small-scale robot on-demand”, US20220184360A1, Filed, Dec 13, 2021.
8. **Y. Shen**, J. Shi, P. Wang, X. Yang, “Underwater vehicle with front-rear distributed drive”, US11772761B2, Granted, Oct 3, 2023.
9. **Y. Shen**, J. Shi, P. Wang, X. Yang, “Hetero-stiffness robotic device”, US11685491B2, Granted, Jun 27, 2023.
10. **Y. Shen**, Y. Yan, J. Pan, “Electromechanical sensor and a method of sensing an object or a tactile input using the sensor”, US11668554B2, Granted, Jun 6, 2023.
11. **Y. Shen**, H. Lu, “System and method for ankle rehabilitation”, US 11471359B2, Granted, Oct. 18, 2022.
12. **Y. Shen**, X. Yang, H. Lu, “Soft body robotic device”, US 011361893B2, Granted, Jun 14, 2022.
13. **Y. Shen**, G. Dai, W. Wan, “Substrate for a three-dimensional cell culture, its preparation and use”, US 011280017B2, Granted, Mar 22, 2022.
14. **Y. Shen**, H. Lu, “Method for use in optical imaging, a system for using in optical imaging and an optical system”, US 011079584B2, Granted, Aug 3, 2021.
15. **Y. Shen**, W. Wan, L. Zhang, “System and method for manipulating an object for imaging”, US20170176733A1, Granted, Mar 20, 2018.
16. **Y. Shen**, “Used for the backend drive devices, control systems, methods, and robots of the robot”, CN 2023103351206, Filed, Mar 31, 2023.
17. **Y. Shen**, “Probe, probe robot, catheter robot, robotic system, and detection system”, CN 2023103351155, Filed, Mar 31, 2023.
18. **Y. Shen**, Z. Wang, L. Wang, Y. Yang, M. Zhang, “Preparation of 3D Structural Materials Based on Graphene Oxide and Composite Shells”, CN 110624125B, Granted, Mar 4, 2022.
19. **Y. Shen**, H. Lu, “Rotary device and method for single cell injection”, CN 108504538B, Granted, Jun 18, 2021.
20. **Y. Shen**, H. Lu, “In situ loading and characterization device for micro-nano material”, CN 108572106B, Granted, July 10, 2020.
21. **Y. Shen**, H. Lu, “Sample stage, imaging instrument and their adjustment method”, CN 108020252B, Granted, Mar 6, 2020.
22. **Y. Shen**, L. Zhang, “A high frequency fatigue testing and a micro morphology imaging device”, CN 105738229B, Granted, Nov 9, 2018.
23. **Y. Shen**, L. Zhang, W. Wan, “An in-situ twisting and imaging device for micro/nano material”, CN 105606459B, Granted, July 13, 2018.

## EXTERNAL SERVICE

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- Senior Member of IEEE, IEEE Distinguished Lecturer; Vice-Chair of IEEE Hong Kong Magnetics Chapter (2023 - present), Co-Chair of the IEEE Nano Technology Council Nano-Biomedicine TC (2022 - present), etc; Executive Council of China Micro-nano Robotic Society, China Micro-nano Fabrication Society, China Instrument Sensor Society, China Coexisting-Cooperative-Cognitive Robotic Society, China Automation Society Robotic TC, etc.

- Associate Editor of IEEE Trans on Robotics (2019-2022); Editor Board Member of Engineering, Cyborg and Bionic Systems, Frontiers in Robotics and AI, Robot Learning, Sensors, etc; Guest Editor of Micromachines, Journal of Sensors, Microscopy Research, IEEE Trans. on Nanotechnology (SI: Micro-Nano robot), International Journal of Advanced Robotic Systems, Journal of Central South University, etc.
- General Chair of IEEE ARSO 2024, Program Co-Chair of IEEE RAAI 2021, Program Co-Chair of IEEE ICMA 2021, Regional Program Chair of IEEE RCAR 2021, Program co-chair of IEEE ICMA 2020, Local chair of IEEE IROS 2019, Program chair of IEEE RCAR 2018, Program co-chair of IEEE Cyber 2017, Industry forum co-chair of IEEE Nano 2017, Committee member of IEEE 3M-NANO, MARSS for many years, etc.
- Plenary/Keynote/Invited Speech in NanoMed 2025, ICAMchS 2025, ICMA2025, CRS 2025, AIS 2024, ISAF 2024, CAA 2023, MARSS 2023, SoftRob 2023, ICARM 2023, FEIM 2023, iCanX 2023, IFETC 2022, MRB 2020, ICASE 2020, SoftRob 2019, NANO 2019, MARSS 2019, MRS 2018, ICNME 2017, MRB 2017, CYBER 2016, NEMS 2015, ICIDC 2015, etc.
- Reviewer of Nature, Science, Science Robotics, Science Advances, Nature Communications, Nature Machine Intelligence, Nature Electronics, Advanced Science, Advanced Materials, IEEE Transactions, International conference (e.g., ICRA, IROS, Robio, Cyber, etc), etc.

## AWARDS & HONORS

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- **Top 10 Innovation and Technology News in Hong Kong in 2025**, for the work of “sub-millimeter robot” *2025*
- **Fellow of International Academy of Artificial Intelligence Sciences (AAIS)** *2025*
- **Member of The Hong Kong Young Academy of Sciences, HKYAS** *2025*
- **Second Prize of Scientific and Technological Progress**, Chinese Association of Automation *2024*
- **Hong Kong Young Scientist of Entrepreneur**, Hong Kong InnoX Academy *2023*
- **Fellow of HKUST Founders’ Club**, The Hong Kong University of Science and Technology *2023*
- **Teaching Excellent Appreciation Award** for MSc(ELEG) course teaching, The Hong Kong University of Science and Technology *2023*
- **Best UROP Mini-conference Paper Award**, The Hong Kong University of Science and Technology *2023*
- **Outstanding Supervisor Award**, City University of Hong Kong *2020*
- **Excellent Young Scientist (Hong Kong & Macau)**, National Science Foundation of China *2019*
- **IEEE Distinguished Lecturer**, in Robotics and Automation Society *2019*
- **China Top 10 scientific and technological progress in robotics in 2018**, Industry Annual Meeting of China Robot Society *2019*
- **Big-on-Small Award**, International Conference on Manipulation, Automation and Robotics at Small Scale (1 person/year worldwide in the field of micro/nano robotics) *2018*
- **Third Prize**, The 3rd Underwater Robot Competition (as supervisor) *2018*
- **Best Paper Finalist Award**, International Conference on Complex Medical Engineering *2017*
- **Second Prize**, The 10th International Underwater Robot Competition (as supervisor) *2017*
- **Early Career Award**, University Grants Committee of Hong Kong *2014*

- **Best Manipulation Paper Award**, International Conference on Robotics and Automation (Flagship robotic conference, one paper/year, Top 0.5%) *2011*
- **Japan Chapter Young Award**, IEEE Robotics and Automation Society, IEEE (5-10 people/year in Japan) *2011*
- **Best Paper Award**, International Symposium on Micro-Nano Mechatronics and Human Science (one paper/year, TOP 2%) *2009*

## PHD GRADUATES

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<b>REN Hao</b> , PhD	<i>2025</i>
<b>TANG Yifeng</b> , PhD	<i>2025</i>
<b>GUO Dong</b> , PhD	<i>2025</i>
<b>LI Gen</b> , PhD	<i>2024</i>
<b>ZHANG Tieshan</b> , PhD (Excellent Young Scientists Overseas in 2025)	<i>2024</i>
<b>YANG Liu</b> , PhD (Excellent Young Scientists Overseas in 2023)	<i>2022</i>
<b>TAN Rong</b> , PhD (Excellent Young Scientists Overseas in 2025)	<i>2022</i>
<b>YANG Xiong</b> , PhD (Excellent Young Scientists Overseas in 2023)	<i>2022</i>
<b>HUANG Han</b> , PhD	<i>2022</i>
<b>YANG Yuanyuan</b> , PhD	<i>2020</i>
<b>WANG Panbin</b> , PhD	<i>2019</i>
<b>LIU Yanting</b> , PhD	<i>2019</i>
<b>LI Dengfeng</b> , PhD (Excellent Young Scientists Overseas in 2025)	<i>2019</i>
<b>LU Haojian</b> , PhD (Excellent Young Scientists Overseas in 2020)	<i>2019</i>
<b>WAN Wenfeng</b> , PhD	<i>2017</i>